

Geodetic Reference Frames in Presence of Crustal Deformations

Martin Lidberg
Sweden



LANTMÄTERIET

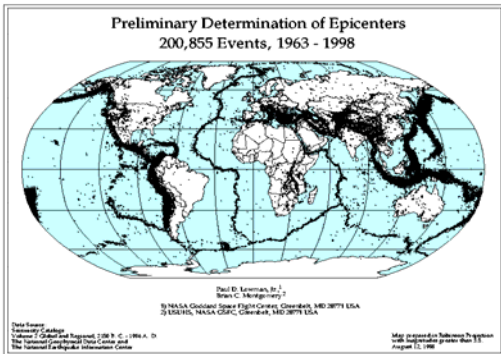
Outline

- Crustal deformations
- Consequences for reference frame management
- Principles for handling the problem
- Case study from the Nordic area
- Summary

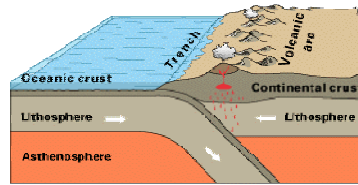


LANTMÄTERIET

Our dynamic planet (1)

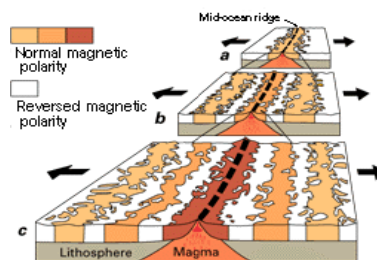


Earthquakes at borders
between tectonic plates



Oceanic-continental convergence

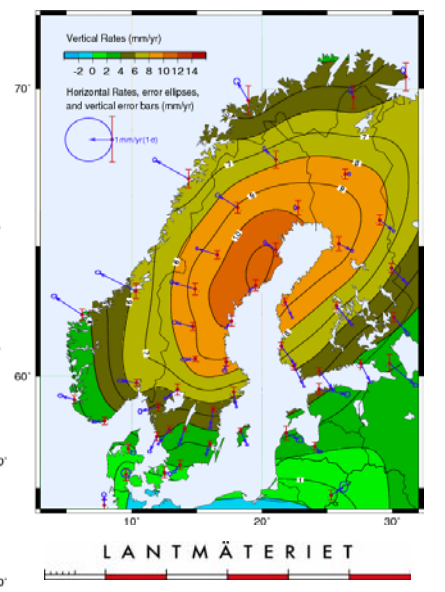
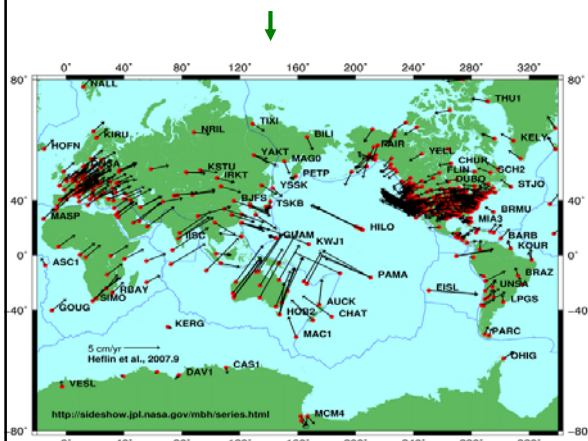
Subduction zone;
Oceanic Ridge



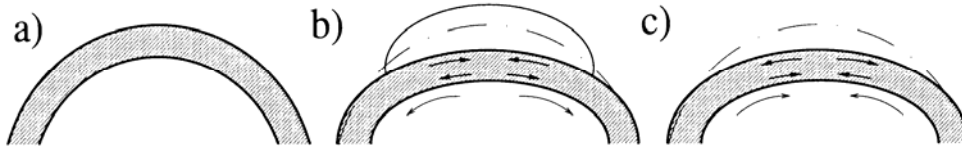
Ts2a_lidberg_ppt_2890.ppt

Our dynamic planet (2)

- The Fennoscandia Post Glacial Rebound
- GPS-observed station velocities



Glacial Isostatic Adjustment (GIA) - or how works the land uplift?



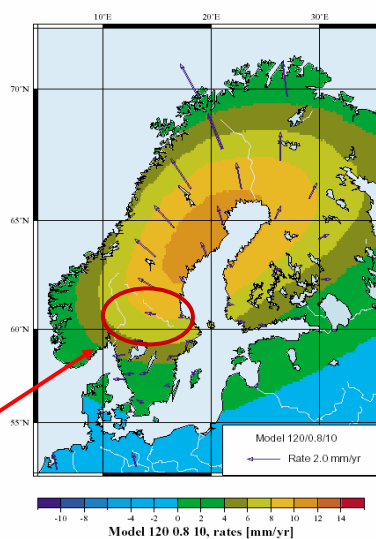
(From Bergstrand, 2002)



- a) The relaxed earth
- b) The earth surface are depressed due to the load from the (1-3 km) ice-sheet (100 000 yr).
- c) The earth rebounds when the ice-load disappeared (10 000 yr)

Consequences for Management of Geodetic Reference Frame

- Position *and* velocities for global reference frames (e.g ITRFxx)
- Regional frames follow the tectonic plate in question (e.g ETRS89 in Europe)
- Intraplate deformations need to be considered (*frames defined using permanent GNSS stations several 100 km apart*)
- For Sweden, 1 cm degradation in positioning over 20 years if Fennoscandian GIA ignored!
- 25 M€ to change geodetic reference frame in Sweden.



Principles for handling the problem

- "Time tag everything!"
- National geodetic reference frame "stable in time" (*users happy!*) but with well defined epoch of validity
- Correct precise measurements from epoch of observation to epoch of the reference frame using a **Velocity Model**
- Estimate the crustal deformations - usually at permanent GNSS sites
- Develop a **Velocity Model** of the deformations (*to interpolate and filter the observed velocities*). Geo-physical model preferred!
- Never use estimated station velocities without modelling for "epoch transformation" !



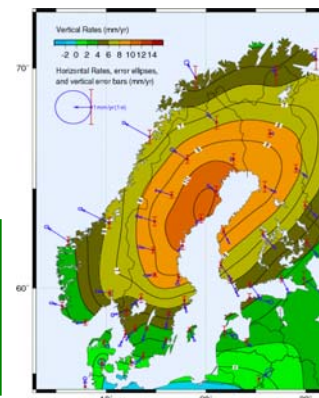
LANTMÄTERIET

Case study: Nordic area

Official national ETRS89:

- Tectonic epoch 1989.0
- Internal deformations ignored (1 cm vertical, 2mm horizontal)

Country	epoch	based on ITRFxx
Denmark	1994.707	ITRF92
Finland	1997.0	ITRF96
Norway	1994.665	ITRF93
Sweden	1999.5	ITRF97



$$\begin{pmatrix} X \\ Y \\ Z \end{pmatrix}_{\text{Epoch}}^{\text{ITRF2000}} = \begin{pmatrix} Y \\ Y \\ Z \end{pmatrix}_{2003.75}^{\text{ITRF2000}} + (\text{Epoch} - 2003.75) \begin{pmatrix} vX_{\text{INTRA}} \\ vY_{\text{INTRA}} \\ vZ_{\text{INTRA}} \end{pmatrix}_{\text{MODEL}}^{\text{ITRF / ETRS}}$$

GNSS stations velocities

GNSS station velocities

- 83 permanent GNSS sites in northern Europe
- Aug 1993-Oct 2006
- GAMIT/GLOBK software
- "checked" using GIPSY software
- *Details in the proceeding paper*

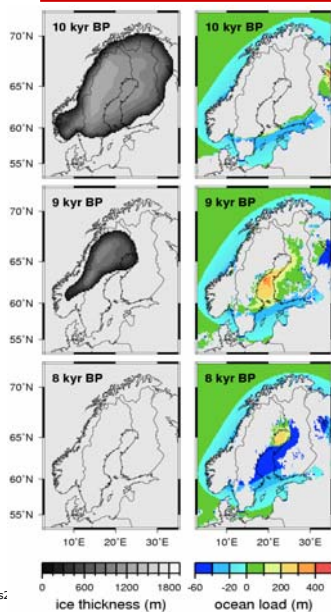
The BIFROST effort:

- Lantmäteriet
- Onsala Space Observatory
- University of Durham
- Finnish Geodetic Institute
- Toronto University
- Smithsonian CfA @ Harvard

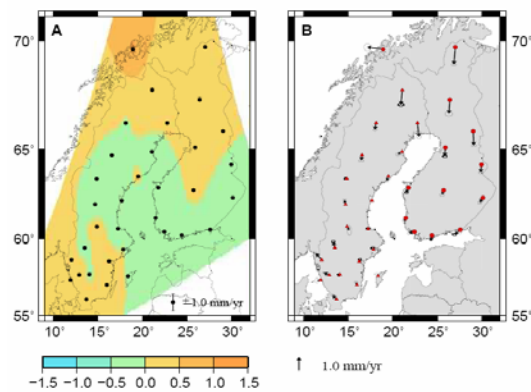


Ts2a_lidberg_ppt_2890.ppt

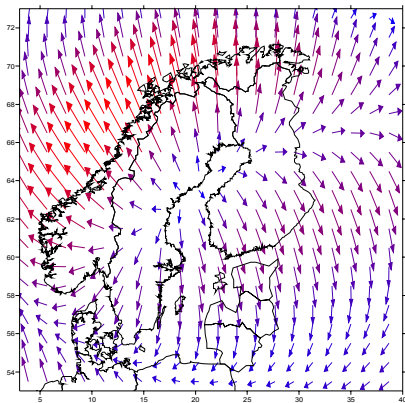
Glacial isostatic adjustment (GIA) model



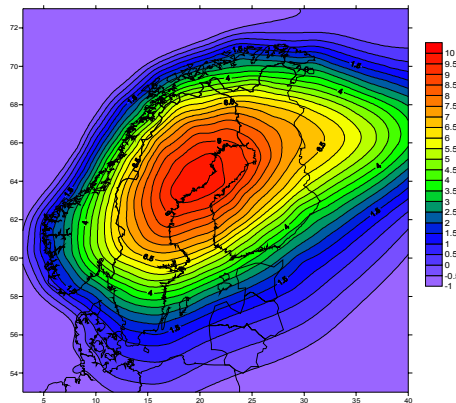
- Ice-load history model (Lambeck 1998)
- 3D GPS station velocities
- Find best fitting (0.5 mm/yr , 1σ) values of:
 - Lithosphere thickness: 120 km
 - upper mantle visc. $5 \times 10^{20} \text{ Pas}$
 - lower mantle visc. $5 \times 10^{21} \text{ Pas}$



Velocity model in grid-format (*.gri)



Horizontal (0 to 2 mm/yr):
GIA model transformed to the
GPS station velocities



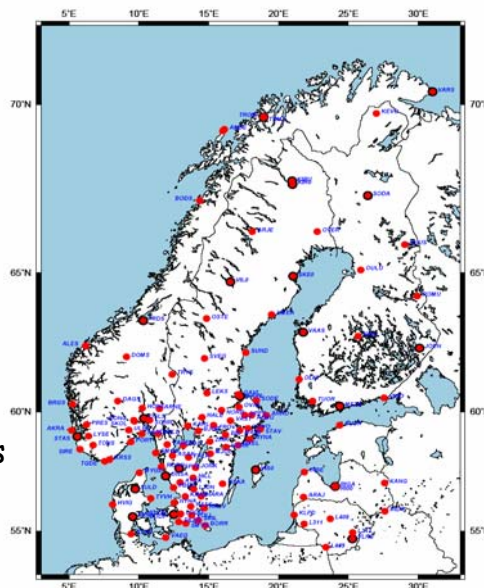
Vertical (-1 to 10 mm/yr):
NKG2005LU(ABS),
Based on: tide gauge, levelling, GPS
NKG w.g. Height determination

Ts2a_lidberg_ppt_2890.ppt

Common campaign to compare the Nordic ETRS89 realizations

Common GPS-campaign:

- "NKG 2003" (Nordic Geodetic Commission)
- 133 stations (Nordic and Baltic area - also Iceland, Greenland and Svalbard)
- GPS week 1238 (w 40, 2003)
- Software: GIPSY, GAMIT, Bernese
- Result in ITRF2000, ep 2003.75
- Coordinated by the NKG w.g. Positioning and Reference Frames



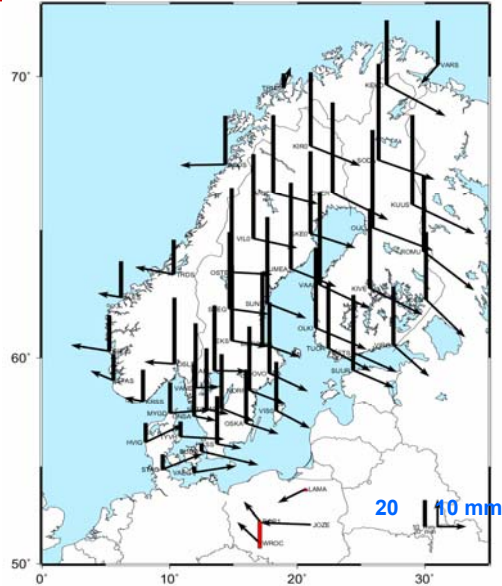
Ts2a_lidberg_ppt_2890.ppt

NKG 2003 vs. official ETRS89 realizations

The NKG 2003 GPS campaign

- in ETRS89 (Boucher & Altamimi MEMO)
- Land uplift ignored
- compared to official national ETRS89 realizations

Mean RMS (mm)	
north	- 4 7
east	9 14
up	42 48



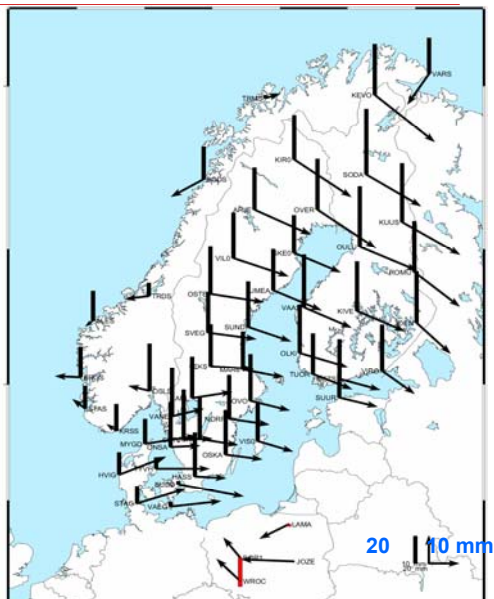
Ts2a_lidberg_ppt_2890.ppt

NKG 2003 vs. official ETRS89 (with internal deformations)

The NKG 2003 GPS campaign

- in ETRS89 (Boucher & Altamimi MEMO)
- internal deformations reduced to year 2000 using the velocity models
- compared to official national ETRS89 realizations

Mean RMS (mm)	
north	- 3 7
east	10 14
up	25 29



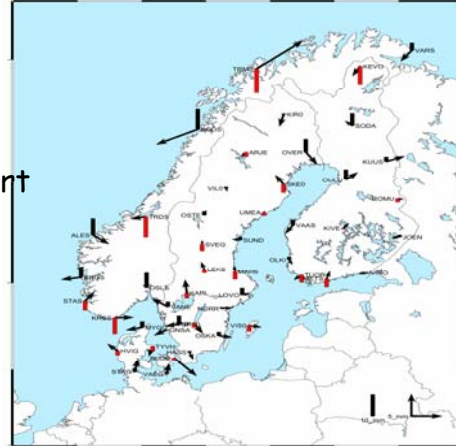
Ts2a_lidberg_ppt_2890.ppt

Each national ETRS89 transformed till NKG 2003

Internal deformations of NKG 2003 GPS campaign reduced to epoch 2000.0

Residuals after 7-parameter Helmert transformation:

RMS (mm)	north	east	up
Denmark (1994.7):	2.5	2.0	1.8
Finland (1997.0):	1.3	1.4	3.7
Norway (1994.6):	2.7	3.9	7.5
Sweden (1999.5):	1.5	1.3	2.5



Ts2a_lidberg_ppt_2890.ppt

Conclusion and outlook

- Crustal deformations must be considered in management of modern Geodetic Reference Frames
- Use a velocity model that **explain** (not only quantify) the crustal deformations
- Model of GIA in Fennoscandia **explain** station velocities based on GPS observations to the 0.5 mm/yr level (1σ)!
- Internal accuracy of the GPS campaigns fulfil ~1-2mm horizontal, and ~5mm vertical
- The challenge is not in the internal geometry of a GNSS network, but in intraplate deformations and reference frame realization!

Ts2a_lidberg_ppt_2890.ppt

LANTMÄTERIET

